Abelian duality for quantum difference equations

1 Hypertoric varieties

In this section, our gauge group is abelian, that is, a torus $T^k \cong (\mathbb{C}^{\times})^k$ of dimension k. Let $V \cong \mathbb{C}^n$ be a faithful representation of T^k given by a collection of characters $\boldsymbol{\chi} = (\chi_1, \ldots, \chi_n)$, that is, by a homomorphism

$$\boldsymbol{\chi}: T^k \to T^n \,. \tag{1}$$

It can be also recorded as a $n \times k$ integer matrix $\boldsymbol{\chi} = (\chi_{i,j})_{i \leq n,j \leq k}$ which describes the induced map of cocharacter lattices. If we want the resulting hypertoric variety to be smooth, we should require

$$k \times k \text{ minors of } \boldsymbol{\chi} \in \{-1, 0, 1\}.$$
 (2)

While a orbifold generalization of the story most certainly exists, we will limit ourselves here to smooth hypertoric varieties.

In particular, this means we can choose a basis in which

$$\boldsymbol{\chi} = \begin{bmatrix} \boldsymbol{1}_{k \times k} \\ \boldsymbol{W} \end{bmatrix} \tag{3}$$

that is, in which the first k rows of χ form a $k \times k$ identity matrix and $W = (w_{ij})$ is a $d \times k$ matrix with

$$|w_{i,j}| \le 1 \tag{4}$$

for all i and j, where d = n - k.

We denote by $A = T^n/T^k$ be the cokernel of the map (1). It acts naturally on X preserving the holomorphic symplectic form. Its fixed points are labelled by k-element subsets of $\{1, \ldots, n\}$ such that the corresponding minor of χ is nonzero. The presentation (3) is thus adapted to one particular fixed point.

2 The integral

 $\mathbf{2.1}$

We denote

$$\phi(x) = (x)_{\infty} = \prod_{n \ge 0} (1 - xq^n)$$

which converges for |q| < 1 and defines an entire function of x known as quantum dilogarithm or the reciprocal of the q-analog of the Γ -function.

We work with integrals of the form

$$I = \int_{\gamma} \mu_z(dt) \prod_{i=1}^n \frac{\phi(\hbar a_i \chi_i(t))}{\phi(a_i \chi_i(t))}$$
(5)

where

$$\mu_z(dt) = e^{-\frac{\langle \ln z, \ln t \rangle}{\ln q}} \prod \frac{dt_i}{2\pi i t_i}$$

the *n*-tuple (a_1, \ldots, a_n) defines an element of T^n and hence of A, \hbar is an element of the group $\mathbb{C}_{\hbar}^{\times}$ that acts by dilating the cotangent direction of T^*V , and

$$\gamma \in H_k(T^k, \{\text{poles}\}, \mathbb{Z})$$

is a cycle of integration invariant under the shift of variables by q.

2.2

With the normalization (3), the integral (5) takes the following form

$$I = \int \mu_z(dt) F \tag{6}$$

where

$$F = \prod_{i=1}^{k} \frac{\phi(\hbar t_i)}{\phi(t_i)} \prod_{i=1}^{d} \frac{\phi(\hbar a_i \mathbf{w}_i)}{\phi(a_i \mathbf{w}_i)} \,. \tag{7}$$

Here $\mathbf{w}_i = \prod t_j^{w_{ij}}$ and we relabeled the coordinates a_i in A to correspond to the last d coordinates in T^n .

3 The difference equation

3.1

The difference equations satisfied by the function F involve shift operators

$$[\nabla_x f](x,\ldots) = f(qx,\ldots)$$

in the variables $x \in \{z_i, a_i\}$. Clearly

$$z_i I = \int \mu_z(dt) \,\nabla_{t_i} F \,, \quad a_i I = \int \mu_z(dt) \,a_i F \,,$$
$$\nabla_{z_i} I = \int \mu_z(dt) \,t_i^{-1} F \,, \quad \nabla_{a_i} I = \int \mu_z(dt) \,\nabla_{a_i} F \,, \tag{8}$$

which means that the difference module generated by the function I is a partial Fourier transform of the difference module generated by the function F.

3.2

Since

$$abla_x \phi(x) = rac{\phi(x)}{1-x},$$

the function F satisfies the following difference equations

$$\left[\nabla_{t_i} - \frac{1 - t_i}{1 - \hbar t_i} \prod_{j=1}^d \frac{(a_j \mathbf{w}_j)_{w_{j_i}}}{(\hbar a_j \mathbf{w}_j)_{w_{j_i}}}\right] F = 0, \quad i = 1, \dots, k,$$
(9)

$$\left[\nabla_{a_i} - \frac{1 - a_i \mathbf{w}_i}{1 - \hbar a_i \mathbf{w}_i}\right] F = 0, \quad i = 1, \dots, d,$$
(10)

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where

$$(x)_k = \prod_{i=0}^{k-1} (1 - q^i x) = \frac{\phi(x)}{\phi(q^k x)}$$

A better way to write the (9) is

$$\left[\nabla_{t_i} - \frac{1 - t_i}{1 - \hbar t_i} \prod_{j=1}^d \nabla_{a_j}^{w_{ij}}\right] F = 0, \quad i = 1, \dots, k,$$
(11)

while (10) is equivalent to

$$\left[\frac{a_i}{\tilde{\hbar}} - \frac{1 - \nabla_{a_i}}{\tilde{\hbar} - \nabla_{a_i}} \prod_{j=1}^k t^{-w_{ij}}\right] F = 0, \quad i = 1, \dots, d,$$
(12)

where $\tilde{\hbar} = q/\hbar$.

3.3

After partial Fourier transform, these become the following equations

$$\left[z_{i} - \frac{1 - \nabla_{z_{i}}}{\hbar - \nabla_{z_{i}}} \prod_{j=1}^{d} \nabla_{a_{j}}^{w_{ij}}\right] I = 0, \quad i = 1, \dots, k,$$
(13)

$$\left[\frac{a_i}{\widetilde{h}} - \frac{1 - \nabla_{a_i}}{\widetilde{h} - \nabla_{a_i}} \prod_{j=1}^k \nabla_{z_i}^{w_{ij}}\right] I = 0, \quad i = 1, \dots, d,$$
(14)

which are symmetric in a and z after

- 1. transposing the matrix W, which means going to the dual hypertoric variety
- 2. exchanging \hbar with $\tilde{\hbar}$, which we always do,
- 3. rescaling the variables a_i .