

2. Warm Up

2.1

$$\begin{array}{c}
 V^k \leftarrow GL(V) \\
 b \downarrow \uparrow a \\
 W^r
 \end{array}
 \quad
 ab = \zeta \quad \text{First assume } \zeta \neq 0$$

$\Rightarrow b: \text{injective} \ \& \ a: \text{surjective}$
 $\therefore k \leq r$

$$(a, b) \mapsto (ga, bg^{-1}) \quad g \in GL(V)$$

Prop $\zeta \neq 0 \quad \{(a, b) \mid ab = \zeta\} / GL(V)$

$$\xleftrightarrow{b_j} \{ \zeta \in \text{End}(W) \mid \zeta \sim \begin{bmatrix} \zeta & & 0 \\ & \zeta_0 & \\ 0 & & 0 \end{bmatrix} \begin{matrix} \{ k \\ \{ r-k \} \end{matrix} \}$$

(Proof) $\zeta := ba \in \text{End}(W)$

$$\zeta^2 = babab = \zeta ba = \zeta \zeta \quad \text{i.e. } \zeta(\zeta - \zeta) = 0$$

$$\begin{array}{l}
 \zeta \neq 0 \\
 \Rightarrow \text{mult. free}
 \end{array}
 \Rightarrow \zeta \sim \begin{bmatrix} \zeta & & 0 \\ & \zeta_0 & \\ 0 & & 0 \end{bmatrix} \begin{matrix} \{ k \\ \{ r-k \} \end{matrix} \quad \text{tr } \zeta = \text{tr}(ab) = k\zeta$$

Conversely if $\zeta \sim \begin{bmatrix} \zeta & & 0 \\ & \zeta_0 & \\ 0 & & 0 \end{bmatrix}$ $\Rightarrow W = (\zeta\text{-eigenspace}) \oplus (0\text{-eigenspace})$

$$\zeta b = bab = \zeta b$$

\therefore up to $GL(V)$ We can set $b = \text{inclusion of } \zeta\text{-eigenspace}$
 $a \zeta = \zeta a \quad a = (\text{proj to } \zeta\text{-eigenspace}) \times \zeta //$

Next assume $b: \text{injective}$

Prop 2 $\{(a, b) \mid ab = 0, b: \text{injective}\} / GL(V)$

$$= \{ (S, \zeta) \mid S \subset W \text{ } k\text{-dim subspace}, \zeta \in \text{End}(W) \quad \zeta(S) = 0, \text{Im } \zeta \subset S \}$$

$$\rightarrow S = \text{Im } b, \quad \bar{z} = ba$$

Exercise : Complete the proof

$$\text{Prop 3 } \{(a, b) \mid ab = 0\} / GL(V)$$

GL(V)-orbit is closed

$$\iff \bar{N} = \{z \in \text{End}(W) \mid z^2 = 0, \text{rk } z \leq k\}$$

(Idea of proof) $\bar{z} = ba \iff z^2 = 0, \text{rk } z \leq k$

Suppose $b = \begin{array}{c|c} \overset{k'}{\underbrace{1 \dots 1}} & \overset{k-k'}{\underbrace{0 \dots 0}} \\ \hline \underset{k-k'}{\underbrace{0 \dots 0}} & \underset{k}{\underbrace{0 \dots 0}} \end{array}$ $0 = ab \iff a = \begin{array}{c|c} \overset{k'}{\underbrace{0 \dots 0}} & \overset{k-k'}{\underbrace{A \dots A}} \\ \hline \underset{k-k'}{\underbrace{B \dots B}} & \underset{k}{\underbrace{C \dots C}} \end{array}$

$$ba = \begin{bmatrix} 0 & A \\ 0 & 0 \end{bmatrix}$$

Thus A is determined, but B & C are not

Now we use the closed orbit condition

$$b = b \cdot \begin{array}{c|c} \overset{k'}{\underbrace{1 \dots 1}} & \overset{k-k'}{\underbrace{0 \dots 0}} \\ \hline \underset{k-k'}{\underbrace{0 \dots 0}} & \underset{k}{\underbrace{t^{-1} \dots t^{-1}}} \end{array} \quad \begin{array}{c|c} \overset{k'}{\underbrace{1 \dots 1}} & \overset{k-k'}{\underbrace{0 \dots 0}} \\ \hline \underset{k-k'}{\underbrace{0 \dots 0}} & \underset{k}{\underbrace{t \dots t}} \end{array} a = \begin{array}{c|c} \overset{k'}{\underbrace{0 \dots 0}} & \overset{k-k'}{\underbrace{A \dots A}} \\ \hline \underset{k-k'}{\underbrace{tB \dots tB}} & \underset{k}{\underbrace{tC \dots tC}} \end{array}$$

$t \rightarrow 0 \quad tB, tC \rightarrow 0$

$\therefore (a, b)$ has closed orbit

$$\Rightarrow B = C = 0$$

(Conversely $B = C = 0 \Rightarrow$ closed orbit)

Exercise Complete the proof.

Remark 4 $z^2 = 0 \Rightarrow \text{rk } z \leq \frac{1}{2}r \quad \therefore \text{rk } z \leq k$ is automatic if $k \geq \frac{r}{2}$

natural to assume $k \leq \frac{r}{2} \iff k \leq r - k$

★ generalization

$$\begin{array}{c}
 V_1 \xrightleftharpoons[C_1]{a} V_2 \xrightleftharpoons[C_2]{b} \dots \xrightleftharpoons[C_{n-1}]{c} V_n \\
 b \downarrow \uparrow a \quad D_1 \quad D_2 \quad \dots \quad D_{n-1} \\
 W
 \end{array}$$

ξ_i : distinct, $\neq 0$

$$\left\{ \begin{array}{l}
 ab = D_1 C_1 + \xi_1 \\
 C_1 D_1 = D_2 C_2 + \xi_2 - \xi_1 \\
 \vdots \\
 C_{n-1} D_{n-1} = \xi_n - \xi_{n-1}
 \end{array} \right.$$

Prop 5 } sol's $\{ \} / GL(V_1) \times \dots \times GL(V_n) \leftrightarrow \{ \xi \in \text{End}(W) \mid \xi \sim \left[\begin{array}{c|c} 0 & \xi_1 \text{id} \\ \hline & \vdots \\ & \xi_n \text{id} \end{array} \right] \}$

$\underbrace{\quad}_n \quad \underbrace{\quad}_m \quad \underbrace{\quad}_1$
 $\underbrace{\quad}_{- \dim V_1} \quad \underbrace{\quad}_{- \dim V_2} \quad \underbrace{\quad}_{\dim V_n}$

Proof) $n=2$ for brevity.

$$\begin{array}{c}
 V_1 \xrightleftharpoons[C_1]{a} V_2 \\
 b \downarrow \uparrow a \quad D_1 \\
 W
 \end{array}$$

$$D_1 C_1 \sim \left[\begin{array}{c|c} (\xi_2 - \xi_1) \text{id} & 0 \\ \hline 0 & 0 \end{array} \right]$$

$$(D_1 C_1)^2 = (\xi_2 - \xi_1) D_1 C_1$$

Set $\xi := ba$ $ab = D_1 C_1 + \xi_1$ $\therefore ab \sim \left[\begin{array}{c|c} \xi_2 \text{id} & 0 \\ \hline 0 & \xi_1 \text{id} \end{array} \right]$

$\therefore \xi \sim \left[\begin{array}{c|c|c} \xi_2 \text{id} & & \\ \hline & \xi_1 \text{id} & \\ \hline & & 0 \end{array} \right] \left\{ \begin{array}{l} \dim V_2 \\ \dim V_1 - \dim V_2 \\ \dim W - \dim V_1 \end{array} \right. \quad (ab - \xi_1)(ab - \xi_2) = 0$

In fact,

$$\begin{aligned}
 \xi(\xi - \xi_1)(\xi - \xi_2) &= \underline{ba} (ba - \xi_1)(ba - \xi_2) \\
 &= b(\underline{ab - \xi_1}) a (ba - \xi_2) \\
 &= b(ab - \xi_1)(ab - \xi_2) a = 0 \quad //
 \end{aligned}$$

Prop 6 { sol's s.t. $b, \mathcal{D}_1, \mathcal{D}_2, \dots, \mathcal{D}_{n-1}$: injective } / $\text{TEGL}(U_i)$

\leftrightarrow bijective T^* (partial flag variety of type $0 < S_n < S_{n-1} < \dots < S_1 < W$ }
 $\dim S_i = \dim U_i$

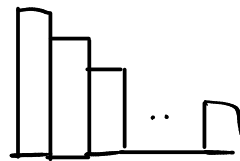
$= \{ (S_0 \text{ as above}, \exists \in \text{End}(W) \mid \exists(S_i) = S_{i+1} \}$
 where $S_0 = W, S_{n+1} = 0$

Next consider generalization of Prop 3.

With regard of Rem 4,

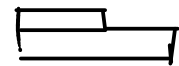
Assume $\dim W \geq \dim U_1 \geq \dim U_2 \geq \dots$
 $-\dim U_1 \quad -\dim U_2 \quad -\dim U_3$

Consider this as a partition



and its transpose μ_1 $\mu_2 \dots$

eg. $r=k$



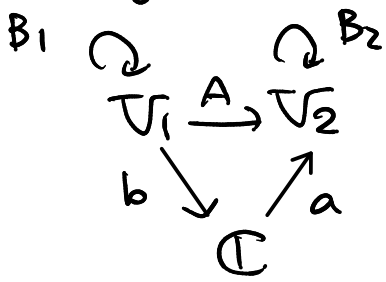
$$\Rightarrow \mu = (\underbrace{2 \dots 2}_k \underbrace{1 \dots 1}_{r-2k})$$

Prop 7 Let $J_\mu = \left[\begin{array}{c|c} \begin{matrix} 0 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 0 \end{matrix} \} \mu_1 & \\ \hline \begin{matrix} 0 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 0 \end{matrix} \} \mu_2 & \\ \vdots & \end{array} \right]$

\Rightarrow { sol's s.t. closed $GL(U_1) \times \dots \times GL(U_n)$ -orbits }
 $GL(U_1) \times \dots \times GL(U_n)$

$\leftrightarrow \overline{J_\mu} = \bigcup_{\nu \leq \mu} J_\nu$ " \leq " dominance order
 closure in $\text{End}(W)$

2.2 Triangle



$$B_2 A - A B_1 + ab = 0$$

$$(S1) \quad B_1(S_1) \subset S_1, \quad A(S_1) = 0 = b(S_1) \\ \Rightarrow S_1 = 0$$

$$(S2) \quad B_2(T_2) \subset T_2, \quad T_2 \supset \text{Im } A + \text{Im } a \\ \Rightarrow T_2 = V_2$$

$$\tilde{\mathcal{M}} \equiv \tilde{\mathcal{M}}_{b_2} = \{(A, B_1, B_2, a, b) \mid \text{above } \}$$

$$\hat{\mathcal{C}} \quad G(V) = GL(V_1) \times GL(V_2)$$

$$v_i = \dim V_i$$

Example $V_1 = 0$ $(S2) \Leftrightarrow \mathbb{C}a + \mathbb{C}B_2 a + \dots = V_2$
 $\Leftrightarrow \langle a, B_2 a, \dots, B_2^{v_2-1} a \rangle$
 basis of V_2

\odot If $\alpha_1 a + \alpha_2 B_2 a + \dots + \alpha_k B_2^{k-1} a = B_2^k a$
 $\Rightarrow B_2^{k+1} a = \alpha_1 B_2 a + \dots + \alpha_{k-1} B_2^{k-1} a + \alpha_k B_2^k a$
 \vdots
 $\langle a, B_2 a, \dots, B_2^{k-1} a \rangle$
 contradicts with $\mathbb{C}a + \dots = V_2$

B_2 is represented as $\left[\begin{array}{ccc|c} 0 & \dots & 0 & * \\ 1 & & & * \\ & \ddots & & \vdots \\ 0 & & 1 & * \end{array} \right] \in GL(V_2)$

Prop Suppose $V_1 = 0 \Rightarrow \tilde{\mathcal{M}}_{tri} \cong GL(V_2) \times \{ \text{matrix of the } \}$
 $\left. \begin{array}{l} \text{matrix of the } \\ \text{above form } \end{array} \right\} u = [a \ B_2 a \ \dots \ B_2^{v_2-1} a]^{-1}$
 $\left. \begin{array}{l} \text{matrix of the } \\ \text{above form } \end{array} \right\} \eta = u B_2 u^{-1}$

Note $\det\left(t - \left[\begin{array}{c|c} 0 & z_1 \\ \vdots & \vdots \\ 0 & z_n \end{array} \right] \right) = t^n - z_n t^{n-1} - \dots - z_1$

$$\left(\begin{array}{l} \det \begin{bmatrix} t & -z_1 \\ -1 & t-z_2 \end{bmatrix} = t^2 - z_2 t - z_1 \\ \det \begin{bmatrix} t & & -z_1 \\ -1 & t & -z_2 \\ & -1 & t-z_3 \end{bmatrix} = t^3 - z_3 t^2 - z_2 t - z_1 \end{array} \right.$$

\therefore eigenvalues with multiplicities determine η

$GL(V_2)$ adjoint action } orbits \leftrightarrow { Jordan normal forms }

$End(V_2)/GL(V_2)$ is not Hausdorff as $GL(V_2)$ -orbit may not be closed

e.g. $\overline{GL(V_2) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}} \ni 0$

More natural to consider

$End(V_2) // GL(V_2) := \overline{End(V_2) / \sim}$

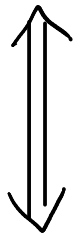
$A \sim B \iff GL(V_2)A \cap GL(V_2)B \neq \emptyset$

In each equivalence class

- $\exists 1$ (smallest) closed orbit ... semi-simple
- $\exists 1$ (largest) open orbit ... regular

$$g \left[\begin{array}{c|c} 0 & z_1 \\ \vdots & \vdots \\ 0 & z_n \end{array} \right] = \left[\begin{array}{c|c} g_{12} & g_{1n} \\ \vdots & \vdots \\ g_{n2} & g_{nn} \end{array} \middle| * \right]$$

$$\left[\begin{array}{c|c} 0 & z_1 \\ \vdots & \vdots \\ 0 & z_n \end{array} \right] g = \left[\begin{array}{c|c} z_1 g_{n1} & \dots \\ z_2 g_{n1} + g_{11} & \dots \\ \vdots & \vdots \\ z_n g_{n1} + g_{n-1,1} & \dots \end{array} \right]$$



g is determined by $\left[\begin{array}{c|c} g_{11} & \\ \vdots & \\ g_{n1} & \end{array} \middle| * \right] \therefore \dim \text{Stab}(g) = n$

\therefore A matrix of the above form is regular.