

★ Supplement
Remark 4

$$\begin{array}{l} \mathcal{V}^k \\ \hookrightarrow \mathcal{A} \\ \mathcal{W}^r \end{array}$$

$$\mathcal{M} = \{(a, b) \mid ab = 0, \text{ closed orbit}\}$$

$$\iff \overline{\mathcal{N}} = \{\mathcal{Z} \mid \mathcal{Z}^2 = 0, \text{rk} \mathcal{Z} \equiv k\}$$

- $\text{rk} \mathcal{Z} = k \Rightarrow GL(\mathcal{V}) \curvearrowright (a, b)$ free
 may assume $b = \begin{bmatrix} 1 & & \\ & \ddots & \\ & & 1 \\ & & & 0 \end{bmatrix}$ $bg = b \Rightarrow g = \text{id}$

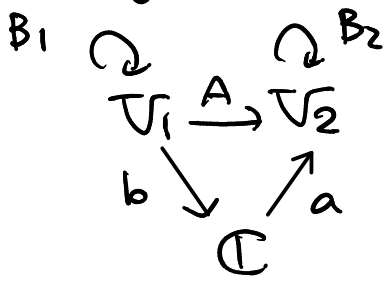
Conversely if $\text{rk} \mathcal{Z} < k$, $GL(\mathcal{V}) \curvearrowright (a, b)$: non-free

⊙ Recall $b = \begin{bmatrix} 1 & \dots & 1 & | & 0 \\ \hline 0 & & & | & a \end{bmatrix} \begin{matrix} k' \\ r-k' \end{matrix}$, $a = \begin{bmatrix} 0 & \mathcal{Z} \\ \hline 0 & 0 \end{bmatrix} \begin{matrix} k' \\ k-k' \end{matrix}$
 $\underbrace{\quad}_{k'} \quad \underbrace{\quad}_{k-k'} \quad (rk b = k')$

$\begin{matrix} k' \\ k-k' \end{matrix} \left(\begin{bmatrix} 1 & | & 0 \\ \hline 0 & | & g \end{bmatrix} \right)$ fixes a, b
 $\underbrace{\quad}_{k'} \quad \underbrace{\quad}_{k-k'}$

- If \exists free orbit $\Rightarrow k \leq \frac{r}{2}$ ($\Leftrightarrow k \leq r-k$)
 (max rank)

2.2 Triangle



$$B_2 A - A B_1 + ab = 0$$

$$(S1) \quad B_1(S_1) \subset S_1, \quad A(S_1) = 0 = b(S_1) \\ \Rightarrow S_1 = 0$$

$$(S2) \quad B_2(T_2) \subset T_2, \quad T_2 \supset \text{Im } A + \text{Im } a \\ \Rightarrow T_2 = V_2$$

$$\tilde{\mathcal{M}} \equiv \tilde{\mathcal{M}}_{tri} = \{ (A, B_1, B_2, a, b) \mid \text{above } \}$$

$$\tilde{G}(V) = GL(V_1) \times GL(V_2) \quad \triangleq \text{not taking quotient}$$

$$v_0 = \dim V_i$$

Example $V_1 = 0 \quad (S2) \Leftrightarrow \mathbb{C}a + \mathbb{C}B_2 a + \dots = V_2$
 $\Leftrightarrow \langle a, B_2 a, \dots, B_2^{v_2-1} a \rangle$
 basis of V_2

\odot If $\alpha_1 a + \alpha_2 B_2 a + \dots + \alpha_k B_2^{k-1} a = B_2^k a$
 $\Rightarrow B_2^{k+1} a = \alpha_1 B_2 a + \dots + \alpha_{k-1} B_2^{k-1} a + \alpha_k B_2^k a$
 \vdots
 $\langle a, B_2 a, \dots, B_2^{v_2-1} a \rangle$
 contradicts with $\mathbb{C}a + \dots = V_2$

B_2 is represented as

$$\left[\begin{array}{cccc|c} 0 & \dots & 0 & & * \\ 1 & & 0 & & * \\ & \ddots & & & \vdots \\ 0 & & & 1 & * \end{array} \right]$$

\mathbb{C}^{v_2}

Prop 1. Suppose $V_1 = 0 \Rightarrow \tilde{\mathcal{M}}_{tri} \cong GL(V_2) \times \{ \text{matrix of the } \}$
 above form
 $(B_2, a) \xrightarrow{GL(V_2)} u \quad \eta = u B_2 u^{-1}$
 $(u^{-1} \eta u, u^{-1} \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}) \longleftarrow (u, \eta)$

Note $\det\left(t - \left[\begin{array}{c|c} 0 & z_1 \\ \vdots & z_2 \\ 0 & \vdots \\ 0 & 1 & z_n \end{array} \right] \right) = t^n - z_n t^{n-1} - \dots - z_1$

$$\begin{cases} \det \begin{bmatrix} t & -z_1 \\ -1 & t-z_2 \end{bmatrix} = t^2 - z_2 t - z_1 \\ \det \begin{bmatrix} t & & -z_1 \\ -1 & t & -z_2 \\ & -1 & t-z_3 \end{bmatrix} = t^3 - z_3 t^2 - z_2 t - z_1 \end{cases}$$

\therefore eigenvalues with multiplicities determine \mathcal{Z}

$GL(V_2) \curvearrowright \text{End}(V_2)$ adjoint action } orbits \leftrightarrow { Jordan normal forms }

$\text{End}(V_2) / GL(V_2)$ is not Hausdorff as $GL(V_2)$ -orbit may not be closed

e.g. $\overline{GL(V_2) \begin{bmatrix} 1 & 0 \\ 0 & \dots & 1 \end{bmatrix}} \ni 0$

More natural to consider

$\text{End}(V_2) // GL(V_2) := \text{End}(V_2) / \sim$

$A \sim B \iff \overline{GL(V_2)A} \cap \overline{GL(V_2)B} \neq \emptyset$

In each equivalence class

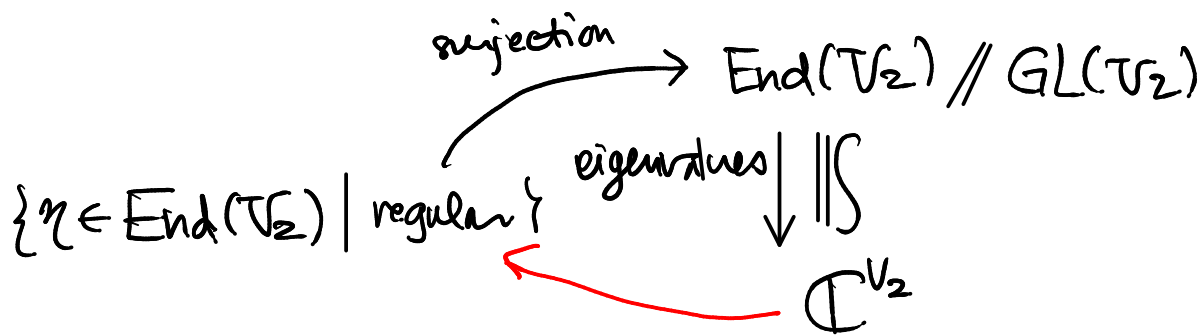
- $\exists 1$ (smallest) closed orbit \dots semisimple
- $\exists 1$ (largest) open orbit \dots regular

$$g \left[\begin{array}{c|c} 0 & z_1 \\ \vdots & \vdots \\ 0 & 1 & z_n \end{array} \right] = \left[\begin{array}{c|c} g_{12} & g_{1n} \\ \vdots & \vdots \\ g_{n2} & g_{nn} \end{array} \middle| * \right]$$

$$\left[\begin{array}{c|c} 0 & z_1 \\ \vdots & \vdots \\ 0 & 1 & z_n \end{array} \right] g = \left[\begin{array}{c|c} z_1 g_{n1} & \dots \\ z_2 g_{n1} + g_{11} & \dots \\ \vdots & \vdots \\ z_n g_{n1} + g_{n-1,1} & \dots \end{array} \right]$$

g is determined by $\left[\begin{array}{c|c} g_{11} \\ \vdots \\ g_{n1} \end{array} \middle| * \right] \therefore \dim \text{Stab}(g) = n$

\therefore A matrix of the above form is regular.



An above form matrix gives a representative of the equiv. rel. \sim

$$J = \begin{bmatrix} 0 & 0 \\ \delta & 1 \end{bmatrix}$$

orbit through N

Also consider $T_N(O(J)) = \{ [Z, \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}] \mid Z \in \mathfrak{gl}(V_2) \}$

$$\begin{bmatrix} z_{12} & \dots & z_{1n} & 0 \\ \vdots & & \vdots & \vdots \\ z_{n2} & \dots & z_{nn} & 0 \end{bmatrix} \cong \begin{bmatrix} 0 & \dots & 0 \\ z_{11} & \dots & z_{1n} \\ \vdots & & \vdots \\ z_{n-1,n} & \dots & z_{n,n} \end{bmatrix}$$

$\cap \left\{ \begin{bmatrix} z_1 \\ \vdots \\ z_n \end{bmatrix} \right\} \Rightarrow z_{12} = \dots = z_{1n} = 0, z_1 = 0$
 $z_{22} = z_{11}, z_{23} = \dots = z_{2n} = 0, z_2 = z_{1n} = 0$
 $\Rightarrow \eta = 0$

• codim orbit in $\text{End}(V_2) = \dim \text{Stab} \begin{bmatrix} 0 & 0 \\ \delta & 1 \end{bmatrix} = n$

$\therefore T_N \text{End}(V_2)$

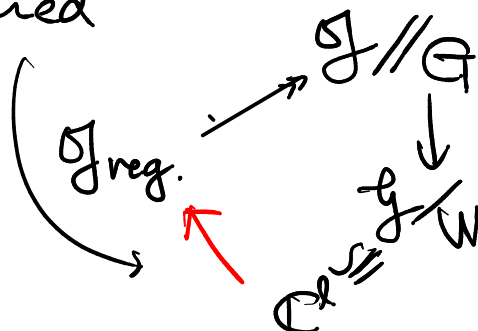
$= T_N(O(J)) \oplus [0 \mid \begin{smallmatrix} * \\ \vdots \\ * \end{smallmatrix}]$



$N = \begin{bmatrix} 0 & z_1 \\ \delta & 1 \\ 0 & z_n \end{bmatrix} = N + \begin{bmatrix} 0 & z_1 \\ \vdots & \vdots \\ 0 & z_n \end{bmatrix}$

This construction is available only in type A.
 For general type Kostant, Slodowy considered

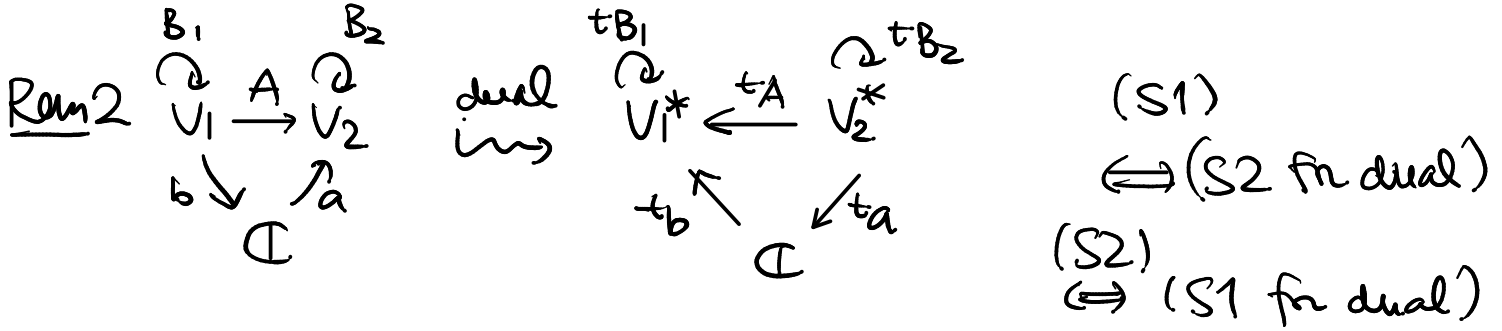
Kostant-Slodowy slice



We say slice

$\widetilde{U}_{\text{fin}} = \text{GL}(V_2) \times \text{slice}$

General case



(S1) $S_1 \subset V_1 \implies B_1(S_1) \subset S_1, b(S_1) = 0 = A(S_1)$
 $\implies S_1 = 0$

\Updownarrow

(S2) $S_1^\perp \subset V_1^* \implies {}^t B_1(S_1^\perp) \subset S_1^\perp, \text{Im } {}^t b \subset S_1^\perp$
 $\text{Im } {}^t A \subset S_1^\perp$

This is (S2) for dual

$(\langle {}^t B_1(t), s \rangle = \langle t, B_1(s) \rangle)$

$\implies S_1^\perp = V_1^*$

Prop 3 $\varphi(A, B_1, B_2, a, b) = B_2 A - A B_1 + a b$

$d\varphi$: surjective on \tilde{M}

Suppose $\exists \in \text{Hom}(V_2, V_1) \perp \text{Im } d\varphi$.

$\implies \text{tr}(\exists(B_2 A + B_2 \dot{A} - \dot{A} B_1 - A \dot{B}_1 + \dot{a} b + a \dot{b}))$

$\implies A \exists = 0, \exists A = 0$

$\exists B_2 = B_1 \exists, b \exists = 0, \exists a = 0$

$\text{Im } \exists \subset \text{Ker } A, \text{Ker } b$

B_1 -inv.

$\implies \text{Im } \exists = 0 \quad //$

Cor 4. \tilde{M} smooth and $\dim \tilde{M} = V_1^2 + V_2^2 + V_1 + V_2$

Lemma 4 [Takayama] A is full rank

(i) Let $\begin{cases} x \in \text{Ker } A \\ y \in \text{Ker } {}^t A \end{cases}$ $0 = \langle (B_2 A - A B_1 + a b) x, y \rangle$
 $= b x \times {}^t a y$

If $\exists y \quad {}^t a y \neq 0 \Rightarrow \forall x \in \text{Ker } A \quad b x = 0$

If $\exists x \quad b x \neq 0 \Rightarrow \forall y \in \text{Ker } {}^t A \quad {}^t a y = 0$

$\therefore \text{Ker } A \subset \text{Ker } b \quad \text{or} \quad \text{Ker } {}^t A \subset \text{Ker } {}^t a$

$$\begin{array}{ccc} \downarrow & & \downarrow \\ B_1(\text{Ker } A) \subset \text{Ker } A & & {}^t B_2(\text{Ker } {}^t A) \subset \text{Ker } {}^t A \\ \uparrow & & \\ B_2 A - A B_1 + a b = 0 & & \end{array}$$

$\therefore \text{Ker } A = \{0\}$ by (S1) or $\text{Ker } {}^t A = \{0\}$ by (S2)
 $\hookrightarrow A$: injective $\hookrightarrow A$: surjective //

Prop 5 [Takayama]

(1) If $V_1 \neq V_2$
 $\tilde{\mathcal{M}}_{\text{tri}} \cong \text{GL}(n) \times \{ \eta \in \mathfrak{gl}(m) \mid \begin{array}{c|c} m & n-m \\ * & 0 \\ \hline * & * \\ 0 & \begin{matrix} 1 & 0 \\ & \ddots \\ 0 & 1 \end{matrix} \end{array} \}$

$n = \max(V_1, V_2)$

$m = \min(V_1, V_2)$

$(A, B_1, B_2, a, b) = \left(-u^{-1} \begin{bmatrix} I_m \\ 0 \end{bmatrix}, \underset{m \times m \text{ block}}{-\eta}, -u^{-1} \eta u, u^{-1} \begin{bmatrix} 0 \\ I_m \end{bmatrix}, [* \dots *] \right)$

(2) If $V_1 = V_2$ $\tilde{\mathcal{M}}_{\text{tri}} \cong \text{GL}(n) \times \mathfrak{gl}(m) \times \mathbb{C}^n \times (\mathbb{C}^n)^*$

$(A, B_1, B_2, a, b) = (u, u^{-1} \eta u, \eta - I J, I, J u)$

(proof) (2) A : isom. \Rightarrow clear

(1) Assume $v_1 < v_2$

$$A : \text{injective} \quad \begin{cases} \bar{u}^{-1} = [A a \ B_2 a \ \dots \ B_2^{v_2-v_1-1} a] \\ \zeta = u B_2 \bar{u}^{-1} \end{cases}$$

S_2

$$B_2 A - A B_2 + a b = 0 \quad \Rightarrow \quad B_2 (\text{Im } A) \subset \text{Im } A + \text{Im } a$$

$$\begin{matrix} & m & n-m \\ m & \begin{bmatrix} * & 0 \\ * & * \\ \vdots & \vdots \\ 0 & 1 \end{bmatrix} & \begin{bmatrix} * \\ * \\ \vdots \\ * \end{bmatrix} \\ n-m & \begin{bmatrix} * & * \\ \vdots & \vdots \\ 0 & 1 \end{bmatrix} & \begin{bmatrix} * \\ * \\ \vdots \\ * \end{bmatrix} \end{matrix}$$

//

$$J := \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \quad \mathcal{O}(N) : \text{adjoint orbit through } N$$

$$T_J \mathcal{O}(J) = \left\{ [\zeta, J] \mid \zeta \in \mathfrak{gl}(n) \right\} = \left\{ \begin{bmatrix} 0 & \zeta_{12} J' \\ -J' \zeta_{21} & [\zeta_{22}, J'] \end{bmatrix} \right\}$$

$$\begin{bmatrix} \zeta_{11} & \zeta_{12} \\ \zeta_{21} & \zeta_{22} \end{bmatrix}$$

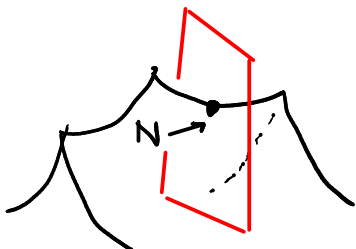
Claim $T_J \text{End}(V_2) = T_J \mathcal{O}(J) \oplus \begin{bmatrix} * & 0 \\ * & 0 \end{bmatrix}$

- $\cap \begin{bmatrix} * & 0 \\ * & * \\ 0 & 0 \end{bmatrix} = 0$
 - (m, m) -block = 0
 - The last column of $\zeta_{12} J' = 0$
 - The 1st row of $J' \zeta_{21} = 0$
 - $\{ [\zeta_{22}, J'] \} \cap \begin{bmatrix} 0 & * \\ * & * \end{bmatrix} = \{0\}$

◦ $\text{codim } \mathcal{O}(J) = \dim \text{Stab}(J)$

$$\begin{bmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & J' \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & J' \end{bmatrix} \begin{bmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{bmatrix} \Leftrightarrow \begin{cases} g_{12} J' = 0, J' g_{21} = 0 \\ g_{22} J' = J' g_{22} \end{cases}$$

$$\therefore 2v_1 + v_1^2 + (v_2 - v_1) \dim$$



NB slice \cap bigger orbits are no longer a single point

Example 6 $\dim V_1 = 1$, $\dim V_2 = n$ ($m=1$)

$$\eta = \begin{bmatrix} a & & & \eta_1 \\ \zeta & 1 & & \vdots \\ & & \ddots & \vdots \\ & & & 1 & \eta_n \end{bmatrix}$$

$$\det(t - \eta) = (t - a)(t^{n-1} - \eta_n t^{n-2} - \dots - \eta_2) + \zeta \eta_1$$

$$\det \begin{bmatrix} t - a & -\eta_1 \\ -\zeta & t - \eta_2 \end{bmatrix} = (t - a)(t - \eta_2) + \zeta \eta_1$$

$$= t^2 - (a + \eta_2)t + a\eta_2 + \zeta \eta_1$$

$$\det \begin{bmatrix} t - a & 0 & -\eta_1 \\ -\zeta & t & -\eta_2 \\ 0 & -1 & t - \eta_3 \end{bmatrix} = t(t - a)(t - \eta_3) + \zeta \eta_1 - \eta_2(t - a)$$

$$= (t - a)(t^2 - \eta_3 t - \eta_2) + \zeta \eta_1$$

$$\det \begin{bmatrix} t - a & & & -\eta_1 \\ -\zeta & t & & \vdots \\ & & \ddots & \vdots \\ & & & 1 & t - \eta_{n-1} \\ & & & -1 & t - \eta_n \end{bmatrix} = (t - a)(t^{n-1} - \eta_n t^{n-2} - \dots - \eta_2)$$

$$+ \zeta \det \begin{bmatrix} 0 & \dots & 0 & -\eta_1 \\ -1 & t & & 0 & t - \eta_3 \\ & & \ddots & & \vdots \\ 0 & & & -1 & t - \eta_n \end{bmatrix}$$

$$= (t - a)(t^{n-1} - \eta_n t^{n-2} - \dots - \eta_2) + \zeta \eta_1$$

$$= t^n - (a + \eta_n)t^{n-1} - (a\eta_n + \eta_{n-1})t^{n-2} + \dots + a\eta_2 + \zeta \eta_1$$

\therefore nilpotent \cap slice

$$a + \eta_n = 0$$

$$a\eta_n + \eta_{n-1} = 0$$

\vdots

$$a\eta_2 + \zeta \eta_1 = 0$$

$$\zeta \eta_1 = (-a)^n$$

$$\parallel \\ (-a)^{n-1}$$

Type A_n hypersurface

in general

in \mathbb{C}^3

(eigenvalues) \cap S : deformation are fixed

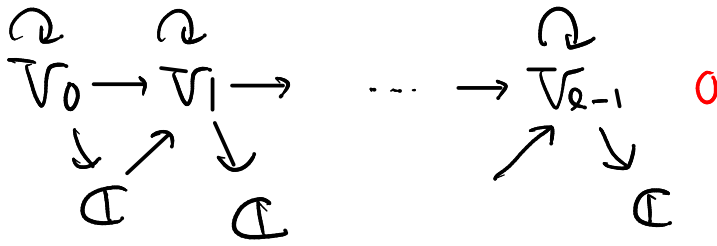
Symplectic form

$M_{\mathbb{R}^2}$ has a symplectic form defined by

$$\left\{ \begin{array}{l} \text{tr}(d\eta \wedge du \bar{u}^T + \eta \, du \bar{u}^T \wedge du \bar{u}^T) \quad v_1 \neq v_2 \\ \text{tr}(d\eta \wedge du \bar{u}^T + \eta \, du \bar{u}^T \wedge du \bar{u}^T + dI \wedge dJ) \quad v_1 = v_2 \end{array} \right.$$

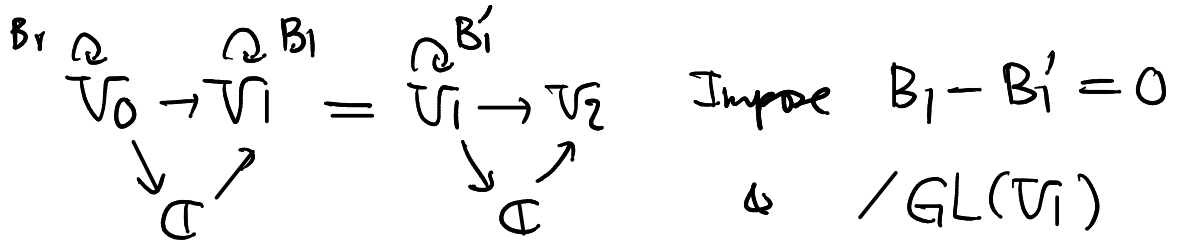
$GL(U_1) \times GL(U_2)$ -action is hamiltonian
moment map is given by $(-B_1, B_2)$

Generalization



$\tilde{\mathcal{M}} =$ each triangle : same as before
 $/ GL(V_1) \times \dots \times GL(V_{k-1})$ not quotient by $GL(V_0)$

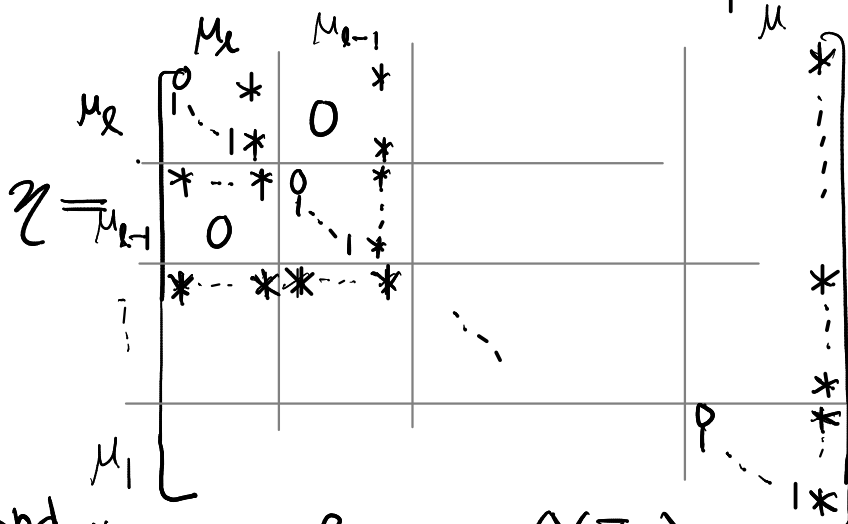
This can be viewed as a hamiltonian reduction :



Assume $\dim V_0 - \dim V_1 \geq \dim V_1 - \dim V_2 \geq \dots \geq \dim V_{k-2} - \dim V_{k-1} \geq \dim V_{k-1} > 0$

$\mu_1' \qquad \mu_2 \qquad \mu_{k-1} \qquad \mu_k$

Prop 7(1) $\tilde{\mathcal{M}} = GL(V_0) \times \{ \mathcal{Z} \in \text{End}(V_0) \mid$



This is true under a weaker assumption $\dim V_0 > \dim V_1 > \dots > \dim V_k$

(2) 2nd term : slice to $O(\mathcal{J}_\mu)$

