

§3. Cherkis bow varieties

3.1 Definition

Example 1 combine examples studied in §2 Warm up.

$$\mathcal{M} = V_1 \overset{\square}{\leftarrow} V_2 \overset{\square}{\leftarrow} \cdots \overset{\square}{\leftarrow} V_m \xrightarrow{D} V_{m+1} \xrightarrow{\square} \cdots \xrightarrow{\square} V_m \xrightarrow{\square} 0$$

$C \square B = 0$

$\sqrt{\prod GL(V_i)}$

$$V_1 \overset{\square}{\leftarrow} \cdots \overset{\square}{\leftarrow} V_{n-1} \times V_n \overset{\square}{\rightarrow} V_{n+1} \rightarrow \cdots \overset{\square}{\rightarrow} V_m \xrightarrow{\square} 0$$

$\downarrow \Gamma$

V_n

quotient
by $GL(V_1) \times \cdots \times GL(V_{n-1})$

$$\begin{matrix} \\ \parallel \\ M \end{matrix}$$

quotient by
 $GL(V_{n+1}) \times \cdots \times GL(V_m)$

$\begin{matrix} \\ \parallel \\ \tilde{M}_{\text{tri}} \end{matrix}$

impose $CD + B = 0$
and take the quotient by $GL(V_n)$

$$M \subset GL(V_n)$$

symplectic hamiltonian

$$\tilde{M} \subset GL(V_n)$$

" "

CD = moment map

B = moment map

$\therefore M = \text{hamiltonian reduction}$

of $M \times \tilde{M}_{\text{tri}}$ by

the diagonal $GL(V_n)$
- action

Examples

$$M = N(J_\lambda)$$

$$\hookrightarrow GL(V_n)$$

$$\tilde{M}_{\text{tri}} = GL(V_n) \times S(J_\mu) \xrightarrow{\text{2nd proj.}} GL(V_n)$$

$$\therefore M = N(J_\lambda) \cap S(J_\mu)$$

Here λ and μ are given as follows

$$\dim V_1 \leq \dim V_2 \leq \cdots \leq \dim V_n$$

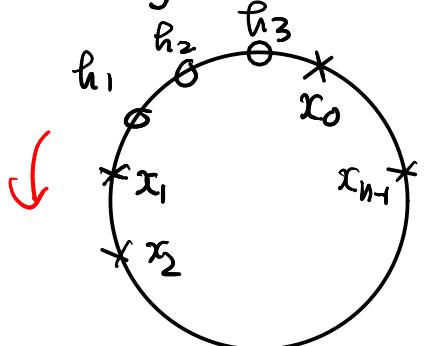
$$-\dim V_1 \quad -\dim V_{n-1}$$

$$\begin{matrix} \parallel \\ t\lambda_n \end{matrix} \quad \begin{matrix} \parallel \\ t\lambda_{n-1} \end{matrix} \quad \begin{matrix} \parallel \\ t\lambda_1 \end{matrix}$$

$$\begin{matrix} \dim V_n \\ -\dim V_{n+1} \\ \parallel \\ \mu_1 \end{matrix} \geq \begin{matrix} \dim V_{n-1} \\ -\dim V_{n-2} \\ \parallel \\ \mu_2 \end{matrix} \geq \cdots \geq \begin{matrix} \dim V_m \\ \parallel \\ \mu_{m-n+1} \end{matrix}$$

Def. 2

○ bow diagram



x_i : anti-clockwise $0 \leq i \leq n-1$

h_σ : clockwise order $1 \leq \sigma \leq 2$

ζ : segment $x \rightarrow o \rightarrow x$

$$\underline{v} = (v_\zeta) \quad v_\zeta \in \mathbb{Z}_{\geq 0} \quad T_\zeta : \text{cpx vector sp dim} = \zeta$$

We divide the circle at the middle of segments

$$\begin{matrix} \xrightarrow{\hspace{1cm}} & \rightsquigarrow & \widetilde{M}_{tw} = \text{Hom}(V_\zeta, V_{\zeta'}) \oplus \text{Hom}(V_{\zeta'}, V_\zeta) \\ v_\zeta & & \\ \xleftarrow{\hspace{1cm}} & & V_\zeta \leftrightarrow V_{\zeta'} \quad \hookleftarrow \text{GL}(V_\zeta) \times \text{GL}(V_{\zeta'}) \end{matrix}$$

$$\begin{matrix} \xrightarrow{\hspace{1cm}} & \rightsquigarrow & \widetilde{M}_{tri} \\ v_\zeta & & \\ \xleftarrow{\hspace{1cm}} & & = \left\{ \begin{matrix} \uparrow & \downarrow \\ V_\zeta \rightarrow V_{\zeta'}, & V_{\zeta'} \rightarrow V_\zeta \\ \downarrow & \uparrow \end{matrix} \right\} \quad \parallel \end{matrix}$$

$\Pi \tilde{M}_{tw} \times \tilde{M}_{tr} \leftarrow$ hamiltonian reduction
by $\mathrm{TGL}(V_3)$

More concretely

$$\begin{array}{c}
 \text{B: common} \\
 \xrightarrow{\quad} \curvearrowright \xrightarrow{\quad} \\
 \text{or} \quad \xrightarrow{\quad} \xrightarrow{C_h} \curvearrowright \xrightarrow{\quad} \\
 \end{array}
 \quad
 \begin{array}{c}
 B \\
 \xrightarrow{\quad} \curvearrowright \xrightarrow{C_h} \\
 D_h \xleftarrow{\quad} \\
 \text{or} \quad \xrightarrow{C_h} \xrightarrow{\quad} D_h \xleftarrow{\quad} \\
 \end{array}
 \quad
 \begin{array}{l}
 \text{5: segment} \\
 DC_h + B_{o(h)} = 0 \quad \text{or} \quad V_h^C \\
 C_h D_h - V_h^C \\
 C_h D_h - V_{h'}^C \\
 = D_h C_{h'} - V_{h'}^C
 \end{array}$$

detoured version

We can deform the defining equation by introducing deformation parameters V_h^C for each $h=0$

$$(B + V_h^C)A - AB + ab = 0$$

Similarly we can introduce a stability condition when we take quotients.

But only for two way parts except one

$$V_h^R (h=0), V_*^R$$

overall shift is irrelevant

1 parameter in total

We will not write down a general stability cond.
give only 2 kinds of stability conditions:

@ $\mathcal{V}R = 0$... affine algebro-geometric quotient
 Ⓛ positive $\nexists_{\text{orbits}} S = \bigoplus S_S \subset \bigoplus \mathcal{V}_S$) closed orbits
 st. invariant under A, C, D
 $b(S) = 0$
 and $S_{0(x)} \xrightarrow{\cong} S_i(x)$
 $\cap \quad \cap$
 $T_{0(x)} \xrightarrow{A} A_{i(x)}$

These give different quotient spaces

M : type @ \tilde{M} : type Ⓛ M^{V^c} : parameter space
 (affine algebraic variety quasi projective variety
smooth

We have a natural map (projective morphism)

$\pi: \tilde{M} \rightarrow M$ smallest orbit in the orbit closure.

Prop 3 type Ⓛ : stabilizer is trivial
 :: Suppose $g_i(x) A_x = A_x g_0(x)$
 $g_S B_S = B_S g_S$

$$T_{0(x)} \xrightarrow{A_x} T_{i(x)} \xrightarrow{a_x} T_{j(x)}$$

$$g_i(x) A_x = Q_x$$

$$b_x = b_x g_0(x)$$

$S_S := \text{Im}(g_S - \text{id})$ ← invariant
 $T_S := \text{Ker}(g_S - \text{id})$ ← under A, B, C, D

$$b(S) = 0$$

$$T_S \text{ is } \mathbb{Q}$$

Lemma 4 $S_{0(x)} \xrightarrow{\cong} S_i(x)$, $T_{0(x)} \xrightarrow{\cong} T_{i(x)}$ for

$$\begin{array}{ccc} \mathbb{Q} & & \mathbb{Q} \\ T_{0(x)} & \xrightarrow{\cong} & T_{i(x)} \\ \downarrow & & \uparrow \\ \mathbb{C} & & \mathbb{C} \end{array}$$

$\dim S_0(x) \leq \dim S_i(x)$
 as if $\ker A_{0S} \neq 0$
 $\text{codim } T_0(x) \geq \text{codim } T_i(x)$

$$\overline{T_i(x)} \xrightarrow{+A_{0S}} \overline{T_0(x)}^{\perp}$$

\cap

$$T_{i(x)}^*$$

$$\begin{aligned} \text{But } \dim S_j &= \dim T_j - \dim T_j \\ &= \text{codim } T_j \end{aligned}$$

\therefore both are $=$ //

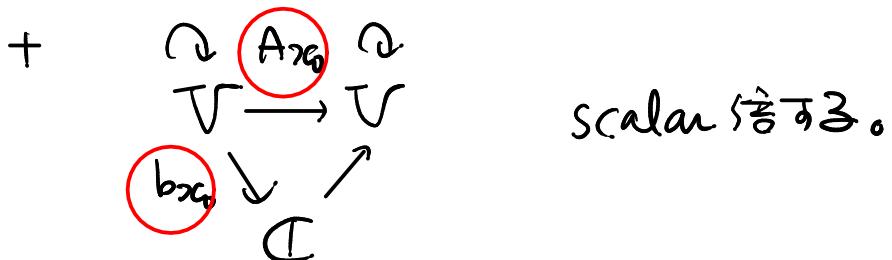
Lemma 4 \Rightarrow Prop 3

GIT theory $\rightsquigarrow \widetilde{M}$ is smooth
 $\pi: \widetilde{M} \rightarrow M$ is a proper map.

Torus action

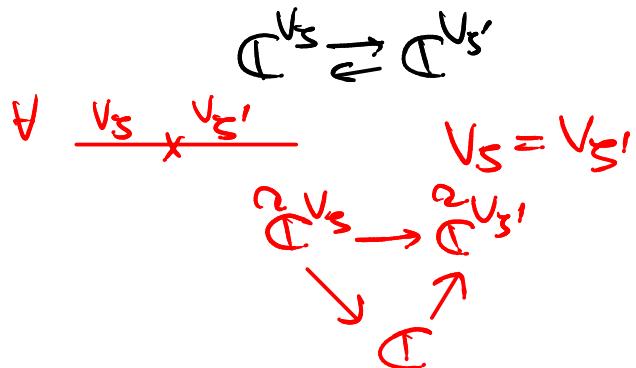
\mathbb{C}^\times acting for \mathbb{C} in each triangle $(\mathbb{C}^\times)^n$

But the diagonal $\mathbb{C}^\times \subset (\mathbb{C}^\times)^n$ acts trivially
 as it can be absorbed to $\prod_S \text{GL}(T_S)$



Def A bow diagram is **cobalanced**

$$\Leftrightarrow \text{V } v_s \xrightarrow{\quad} v_{s'} \quad v_s = v_{s'}$$



Prop5. If the cobalanced cond. is satisfied ,
 $M \cong$ a given variety of affine type A

\because Recall $\begin{matrix} \text{C} \\ \text{V}_1 \rightarrow \text{V}_2 \\ \downarrow \\ \text{C} \end{matrix} \cong \text{GL}(\text{V}_1) \times \text{gl}(\text{V}_1) \times \text{V}_1 \times \text{V}_1^*$

$\underbrace{\qquad\qquad\qquad}_{\text{if } \dim \text{V}_1 = \dim \text{V}_2}$

This factor is killed by
 the hamiltonian reduction
 by $\text{GL}(\text{V}_1)$

So we can replace this by

$$\begin{matrix} \text{V}_2 \\ \downarrow \uparrow \text{J} \\ \text{C} \end{matrix}$$

$$\begin{matrix} \text{C} & \text{C} & \text{C} \\ \text{V}_1 \rightarrow \text{V}_2 \rightarrow \text{V}_3 \\ \downarrow & \downarrow & \downarrow \\ \text{C} & \text{C} & \text{C} \end{matrix}$$

$$\dim \text{V}_1 = \dim \text{V}_2 = \dim \text{V}_3 \rightsquigarrow \begin{matrix} \text{V}_3 \\ \uparrow \downarrow \\ \text{C}^2 \end{matrix}$$

Example

$$\begin{matrix} n=1 \\ \text{V} \\ \text{V} \\ \text{V} \\ \text{V} \end{matrix} \approx \begin{matrix} \text{C} \\ \text{V} \\ \downarrow \\ \text{C}^n \end{matrix}$$

ADHM descr.
 of $SU(n)$ inst
 on \mathbb{R}^4
 or rank framed
 sheaves on \mathbb{CP}^2

3.2 factorization morphism

◦ triangle

$$\begin{array}{ccc} B_1 & \xrightarrow{\quad} & B_2 \\ V_1 \xrightarrow{\quad} & & V_2 \\ b \downarrow & A & \nearrow a \\ C & & \end{array}$$

$$v_i = \dim V_i$$

$$\underline{v} = (v_1, v_2)$$

Define $\Phi: \widetilde{\mathcal{M}}_{\text{tri}}(\underline{v}) \rightarrow \mathbb{C}^{\underline{v}} := \mathbb{C}^{V_1}/\langle \zeta_{v_1} \rangle \times \mathbb{C}^{V_2}/\langle \zeta_{v_2} \rangle$

by eigenvalues of B_1, B_2 counted with multiplicities

We consider a point of $\mathbb{C}^{\underline{v}}$
as a colored configuration in \mathbb{C}
(colored by 1 & 2)

This is invariant under $GL(\underline{v}) = GL(V_1) \times GL(V_2)$

$$\Phi: [\widetilde{\mathcal{M}}_{\text{tri}}(\underline{v}) / GL(\underline{v})] \rightarrow \mathbb{C}^{\underline{v}}$$

(I emphasised that a naive quotient space
does not behave well. This is a stack.

Suppose Eigenvalues of $B_1 = C'_1 + C''_1$

$$\text{s.t. } C'_i \cap C'_{j'} = \emptyset \quad (i, j') = (1, 1), (2, 2), (1, 2), (2, 1)$$

Consider

$$V_1 = V'_1 \oplus V''_1 \quad B_i = \begin{bmatrix} B'_i & 0 \\ 0 & B''_i \end{bmatrix} \quad i=1, 2$$

$$V_2 = V'_2 \oplus V''_2$$

$$a = \begin{bmatrix} a' \\ a'' \end{bmatrix}, \quad b = \begin{bmatrix} b' & b'' \end{bmatrix}$$

$$A = \left[\begin{array}{c|c} A' & A_{12} \\ \hline A_{21} & A'' \end{array} \right]$$

$\begin{cases} (A', B'_1, B'_2, a', b') \\ (A'', B''_1, B''_2, a'', b'') \end{cases}$ are regarded as new data for $\tilde{\mathcal{M}}_{tri}(\underline{v}')$
 (for different dimensions)

Prop 1 (1) (S1, 2) are satisfied. $\leftarrow \frac{\text{exercice}}{A_{12}(S'_1) = 0}$

(2) $\exists 1 A_{12}, A_{21}$ for given other components
 s.t. $B_2 A - AB_1 + ab = 0$

$$(\text{Proof}) \quad B'_1 A_{12} - A_{12} B''_2 + a'b'' = 0$$

$\text{Mat}(v'_1, v''_2) \rightarrow \text{Mat}(v'_1, v''_2)$ is invertible
 $A_{12} \mapsto B'_1 A_{12} - A_{12} B''_2$ as $\text{eigen}(B'_1) \cap \text{eigen}(B''_2) = \emptyset //$

$$(\mathbb{C}^{v'} \times \mathbb{C}^{v''})_{\text{diag}} = \{(C'_1, C'_2, C''_1, C''_2) \in \mathbb{C}^{v'} \times \mathbb{C}^{v''} \mid \text{above cond.}\}$$

$$\text{Cor 2} \quad \tilde{\mathcal{M}}(\underline{v}) \times_{\mathbb{C}^{\underline{v}}} (\mathbb{C}^{v'} \times \mathbb{C}^{v''})_{\text{diag}}$$

$$\cong \tilde{\mathcal{M}}(v') \times \tilde{\mathcal{M}}(v'') \times_{\mathbb{C}^{v'} \times \mathbb{C}^{v''}} (\mathbb{C}^{v'} \times \mathbb{C}^{v''})_{\text{diag}} \times \frac{\text{GL}(\underline{v})}{\text{GL}(v') \times \text{GL}(v'')}$$

$$\text{Recall } \dim \tilde{\mathcal{M}}(\underline{v}) = v_1^2 + v_2^2 + v_1 + v_2 = \dim \text{GL}(\underline{v}) + \underbrace{v_1 + v_2}_{\text{additive}}$$

$\overset{\circ}{\mathbb{C}}^{\underline{v} \text{ det.}} =$ all eigenvalues are distinct

$$\begin{array}{c} \mathbb{C} \\ \curvearrowright \\ \mathbb{C} \\ \downarrow b \neq 0 \\ \mathbb{C} \end{array}$$

$$\begin{array}{c} \mathbb{C} \\ \curvearrowright \\ \mathbb{C} \\ \uparrow a \neq 0 \\ \mathbb{C} \end{array} \leftarrow (\text{S1, 2})$$

Both are $\mathbb{C} \times \mathbb{C}^\times$

$$\text{Cor}^3 \quad \widetilde{\mathcal{M}}(\underline{v}) \times_{\mathbb{P}^{\underline{v}}} \overset{\circ}{\mathbb{C}^{\underline{v}}} \cong \overset{\circ}{\mathbb{C}^{\underline{v}}} \times (\overset{\circ}{\mathbb{C}^{\times} \times \dots \times \mathbb{C}^{\times}} \xrightarrow{\text{GL}(\underline{v})} \overset{(\mathbb{C}^{\times} \times \dots \times \mathbb{C}^{\times})}{\mathbb{C}^{\underline{v}} \times \text{GL}(\underline{v})}) \xrightarrow{\sim v_1 + v_2 \text{ times}}$$

$$\Phi: \widetilde{\mathcal{M}}(\underline{v}) \longrightarrow \overset{\circ}{\mathbb{C}^{\underline{v}}} \quad \text{generic fiber} = \text{GL}(\underline{v})$$

Prop 4. dim. of any fiber = $\dim \text{GL}(\underline{v})$

(sketch) enough to check this when B_1, B_2 are nilpotent
 compute dim when B_1, B_2 : regular nilpotent
 general case \longrightarrow smaller dimension //

o Two way part

$$V_1 \xrightleftharpoons[D]{C} V_2$$

$$B_1 = -DC \quad B_2 = -CD$$

$$\dim V_1 \leq \dim V_2$$

$$\text{tr}_{V_1} (t - CD)^n = \text{tr}_{V_2} (t - DC)^n \\ + t^n (\dim V_1 - \dim V_2)$$

$$\therefore \text{eigen}(B_2) = \text{eigen}(B_1) + \underbrace{(V_2 - V_1)}_{\text{mult. of eigenvalue } 0} 0$$

$$\text{eigen}(B_1) = C'_1 + C''_1$$

$$C'_1 \cap C''_1 = \emptyset$$

$$0 \notin C''_1$$

$$V_1 = V'_1 \oplus V''_1$$

$$V_2 = V'_2 \oplus V''_2$$

$$\text{Prop 5.(1)} \quad C(V'_1) \subset V'_2$$

$$C(V''_1) \subset V''_2$$

$$D(V'_2) \subset V'_1$$

$$D(V''_2) \subset V''_1$$

$$V'_1 \xrightleftharpoons[D]{C'} V'_2$$

$$\oplus \quad \oplus$$

$$V''_1 \xrightleftharpoons[D'']{C''} V''_2$$

$$(2) \quad D'' \leftarrow \cong$$

$$\text{proof)} \quad B_2 C = -CDC = CB_1$$

$$B_1 D = -DCD = DB_2$$

//

$$\Phi: M \longrightarrow \prod_{\mathbb{F}} \mathbb{C}^{V_i(x)} / G_{V_i(x)} \cong \mathbb{C}^r \quad r = \sum_x V_i(x)$$

$[(A, B, C, D, a, b)] \mapsto$ eigenvalues of $B_i(x)$
counted with multiplicities

$$\frac{V_0(x)}{x} \xrightarrow[V_i(x)]{} \begin{matrix} \Omega \\ V_0(x) \end{matrix} \xrightarrow[B_i(x)]{} \begin{matrix} \Omega \\ V_i(x) \end{matrix} \xrightarrow{\quad} \mathbb{C}$$

$$V_0(h) \xrightleftharpoons[D_h]{Ch} V_i(h) \quad \text{tr}_{V_i(h)}(t - (aD_h))^n$$

$$= \text{tr}_{V_i(h)}(t - D_h(a))^n + t^n(\dim V_i(h) - \dim V_0(h))$$

\therefore enough to consider $B_i(x)$

We consider a point of \mathbb{C}^r
as a colored configuration in \mathbb{C}
'colored by x '