

## §5. Analysis of fixed pts / attracting sets

## 5.1 Warm Up

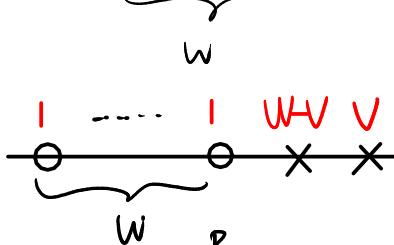
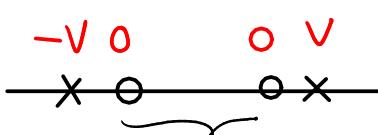
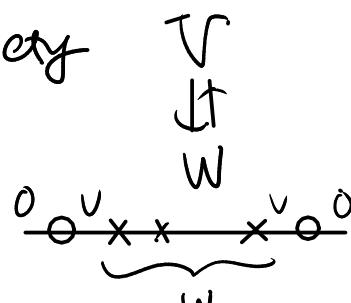
type A,

fliver variety

## cobalanced

$O \hookrightarrow X$

balanced



ie,

$$\begin{array}{c} w \\ \mathbb{C} \rightarrow \mathbb{C}^2 \rightarrow \dots \in \mathbb{C}^{wA} \xrightarrow{\quad} \mathbb{C}^V \\ \downarrow b_1 \qquad \qquad \qquad \uparrow a_1 \qquad \qquad \downarrow b_2 \\ \mathbb{C} \qquad \qquad \qquad \mathbb{C} \qquad \qquad \qquad \mathbb{C} \\ (\mathbb{C}^\times)^2 \rightarrow t_1 \qquad \qquad \qquad t_2 \end{array}$$

Prop

attracting set  $\emptyset$

$\{t_1=t_2\}$  acts trivially  $\Rightarrow t_2=1$

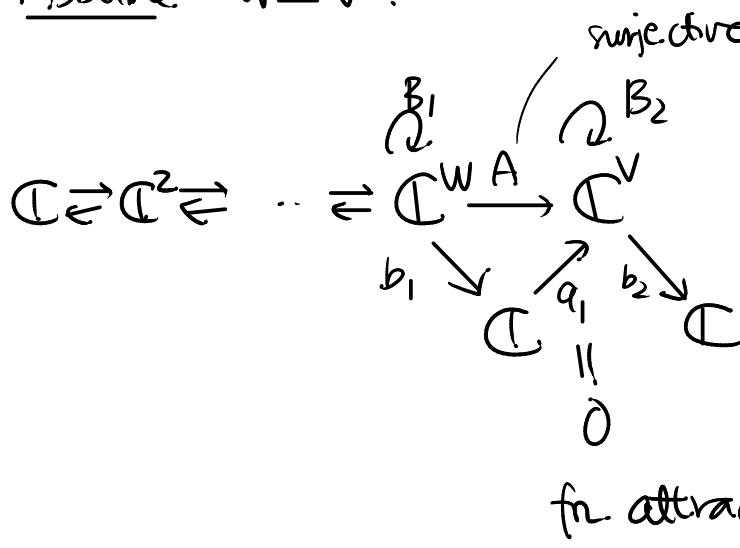
$$b_2 a_1 \mapsto t^\dagger b_2 a_1 \quad \therefore b_2 a_1 = 0$$

$$b_2 \neq 0 \text{ by (S1)}$$

$\therefore A_1 = 0 \quad \therefore B_2 A = AB_1$   
 $\therefore \text{Im } A + \underbrace{\text{Im } A_1}_{=0} \text{ is } B_2 - \text{inv.}$

$\therefore (S2) \Rightarrow A$  : surjective //

Assume  $W \geq V$ .



$B_1$ : nilpotent  
 $B_2 A = AB$ ,  
 $\Rightarrow B_2$  : nilpotent

$\therefore$  by  $GL(V)$  action we can normalise

$$b_2 = [0 \dots 0] \quad B_2 = \begin{bmatrix} 0 & 0 \\ 0 & \ddots \end{bmatrix}$$

basis of  $(C^W)^*$      $b_2 B_2^{V-1} A, b_2 B_2^{V-2} A, \dots, b_2 A$

$$\bullet \quad V < W \quad B_1 = \begin{bmatrix} B_2 & b_1 B_1^{W-V-1} \\ \vdash & \vdash \end{bmatrix}, \dots, b_1$$

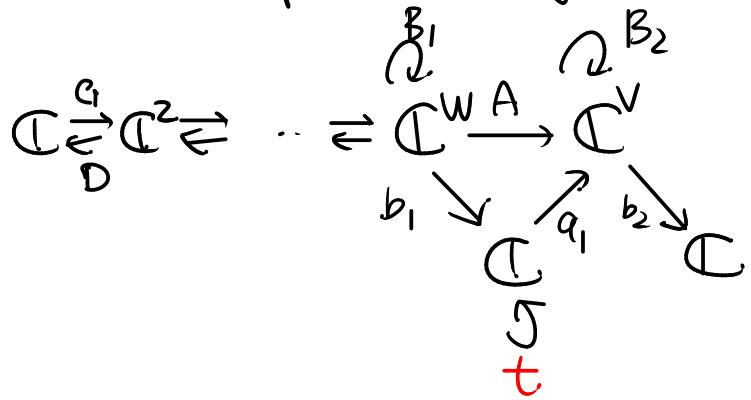
$\therefore A = \text{attracting set} = C^V$

$$\bullet \quad V = W \quad B_1 = \begin{bmatrix} 0 & 0 \\ \ddots & 1 \\ 0 & \ddots & 0 \end{bmatrix} \quad b_1 = [\ast \dots \ast]$$

$\vdash$	$V=0$	$1$	$2$	$\dots$	$W$	$\dots$
$A$	pt	$C$	$C^2$	$\dots$	$C^W$	$\emptyset$

$$\sim \bigoplus_V H_{\text{top}}^{B_1}(A(V,W)) = (\dim \text{irrep of } \Lambda_2)^{\text{dim}}$$

Next we put stability condition:



$$\exists^1 g_1(t), g_2(t), \dots, g_w(t), g_{w+1}(t)$$

$$\text{st. } \begin{cases} g_{i+1}(t) C_i g_i(t)^{-1} = C_i \\ g_i(t) D_i g_{i+1}(t)^{-1} = D_i \\ b_1 g_w(t)^{-1} = t b_1 \\ g_{w+1}(t) a_1 = t a_1 \\ b_2 g_{w+1}(t)^{-1} = b_2 \end{cases}$$

$$g_w(t) B, g_w(t)^{-1} = B_1 \\ g_{w+1}(t) A g_w(t)^{-1} = A$$

Decompose U. spaces according to eigenvalues of  $g(t)$

$$V_i(m) \xrightarrow[D]{C} V_{i+1}(m)$$

$$V_w(m) \xrightarrow[b_1]{0''} \mathbb{C}$$

unless  $m = -1$

$$m=0 \Leftrightarrow -1$$

$$V_1(0) \rightleftarrows V_2(0) \rightleftarrows$$

$$V_1(-1) \rightleftarrows$$

$$V_{w+1}(m) \xrightarrow[b_2=0 \text{ unless } m=0]{\mathbb{C}} \mathbb{C}$$

$$(S1) \Rightarrow \text{only } m=0$$

$$\begin{array}{c} \xrightarrow{\quad B_1 \quad} \xrightarrow{\quad B_2 \quad} \\ \cong \xrightarrow[A]{\quad} \xrightarrow{\quad} \\ \cong \xrightarrow{\quad B_1 \quad} \xrightarrow[b_2]{\quad} \mathbb{C} \\ \text{collapse} \end{array}$$

$B_1, B_2$  : regular w/potent

$$\begin{array}{ccccccc} & 0 & 0 & 1 & 0 & & \\ \hline & \circ & \circ & \circ & \circ & \times & \\ \nearrow & \nearrow & & & & & \\ & 1 & 1 & \oplus & 0 & 1 & \\ \hline & \circ & \circ & \circ & \circ & \times & \end{array}$$

Only 1 or 0 &  $\begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix}$  are not possible

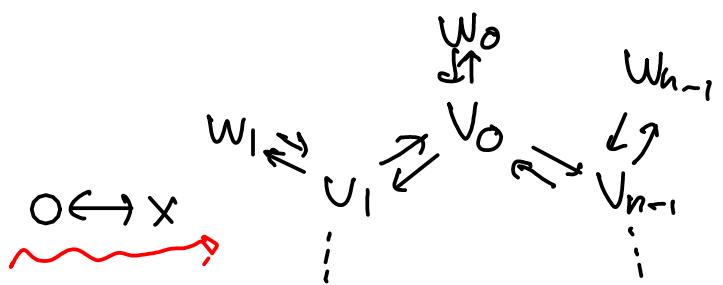
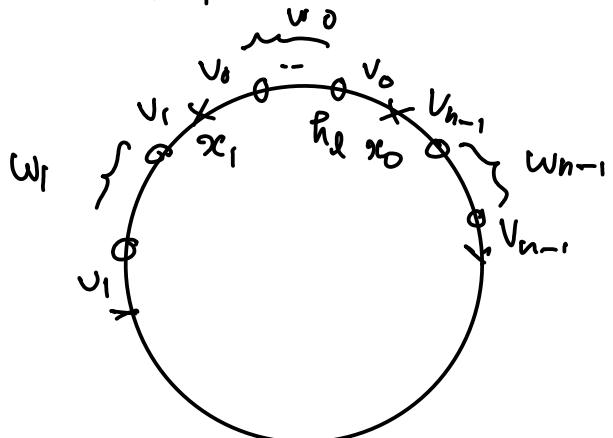
$$\therefore \# \text{fixed pts} = \binom{w}{v}$$

$$= \dim \text{wt space of } \underbrace{\mathbb{C}^2 \otimes \dots \otimes \mathbb{C}^2}_w$$

Compatible with  $\bigoplus_v H_{\text{top}}^{BM}(\widetilde{\mathcal{A}}(v, w)) \cong \underbrace{\mathbb{C}^2 \otimes \dots \otimes \mathbb{C}^2}_w \supset S^w(\mathbb{C}^2)$

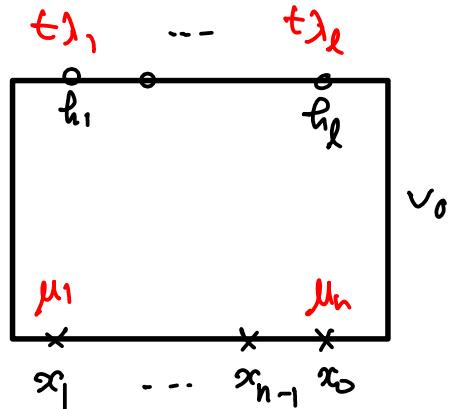
5.2

$\hat{A}_{n-1}$  case



$$l = \#_0 = \sum w_i$$

HW keeping  $x_0$



$$(t_{\lambda_1}, \dots, t_{\lambda_l}) =$$



$$\lambda_1 = w_1 + w_2 + \dots + w_{n-1}$$

$$\lambda_2 = w_2 + \dots + w_{n-1}$$

$$\vdots$$

$$\lambda_{n-1} = w_{n-1}$$

$$\therefore \lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n \geq \lambda_1 - l$$

$$\lambda_n = 0$$

$$\lambda_1 - l = -w_0$$

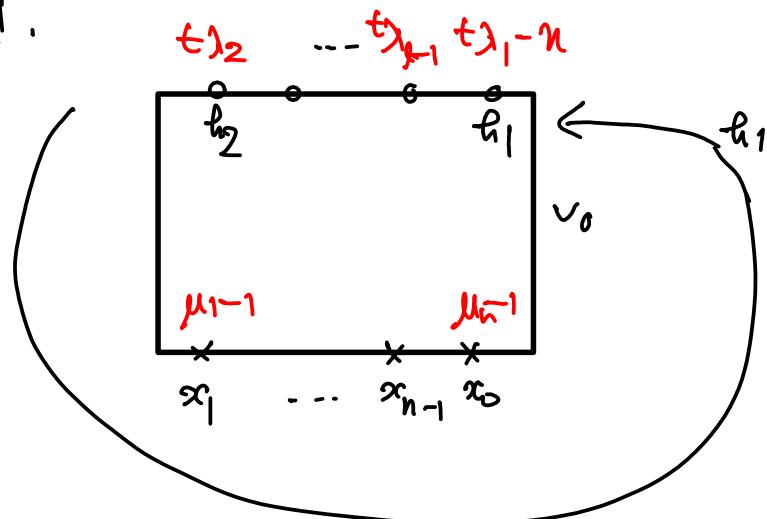
dominance cond. for affine WFs

$$\mu_n = v_{n-1} - v_0 \text{ (because it is unchanged).}$$

Then  $\mu_i = v_{n-1} - v_0 + \sum_{j=i}^{n-1} u_j$        $u_j = w_j + v_{j-1} + v_{j+1} - 2v_j$

$$\text{as } \mu_i - \mu_{i+1} = u_i$$

Remark 1.



$$t_{\lambda_2} \geq \dots \geq t_{\lambda_{k-1}} \geq t_{\lambda_1-n}$$

from now on we don't  
need to assume  
the balanced cond.

Torus action  $\mathbb{C}^\times$  on each  $\mathbb{C}$  for  $\star$  the balanced cond.  
 $\hookrightarrow (\mathbb{C}^\times)^n$  but the  $\Delta$  acts trivially

One additional

$$\begin{array}{ccc} \mathbb{T}_{b_{n-1}} & \xrightarrow{t_{\lambda_{n-1}}^{\star} A_{b_{n-1}}} & \mathbb{T}_0 \\ & \downarrow t_{\lambda_n}^{\star} b_{n-1} & \uparrow A_{b_{n-1}} \\ & \mathbb{C}_{b_{n-1}} & \end{array} \quad \mathbb{T}^n$$

$$\widetilde{\mathcal{M}} : \text{smooth} \hookleftarrow \mathbb{T}^n$$

$[(A, B, a, b, C, D)]$  is fixed

$$\Leftrightarrow \exists_1 \rho : \mathbb{T}^n \rightarrow \mathrm{PGL}(\mathbb{T}_3) \quad \text{as before}$$

$$\rho(t) \curvearrowright \mathbb{T} \quad \text{eigenvalue} : \lambda = t_0^{m_0} t_1^{m_1} \cdots t_{n-1}^{m_{n-1}} t_*^{m_*}$$

$$\mathbb{T}(\lambda) = \text{eigenspace for eigenvalue } \lambda$$

But  $b_{\lambda_i} = 0$  on  $T(\lambda)$ , with  $\lambda \neq t_i$

$$\begin{array}{ccc}
 C \hookrightarrow V_{i-1}(\lambda) & \xrightarrow{\cong} & \overbrace{V_i(\lambda) \oplus S}^{\cong} \\
 & \oplus & \\
 C \hookrightarrow V_{i-1}(t_i) & \longrightarrow & V_i(t_i) \oplus S \\
 & \downarrow & \nearrow \\
 x_i \neq x_0 & & C_{x_i} \\
 & & \\
 x_i = x_0 & \begin{matrix} V_{n-1}(\lambda t_x) \\ \oplus \end{matrix} & \xrightarrow{\cong} V_0(\lambda) \\
 & & \\
 & \begin{matrix} V_{n-1}(t_0 t_x) \\ \oplus \end{matrix} & \longrightarrow V_0(t_0) \\
 & & \\
 & \downarrow & \nearrow \\
 & C_{x_0} &
 \end{array}$$

$$\text{stability condition} \Rightarrow \bigoplus_{n \in \mathbb{Z}} V(\lambda t_*^n) = 0 \quad \text{if } \lambda \neq t_0, t_1, \dots, t_m.$$

We decompose according to  $\lambda = t_i$

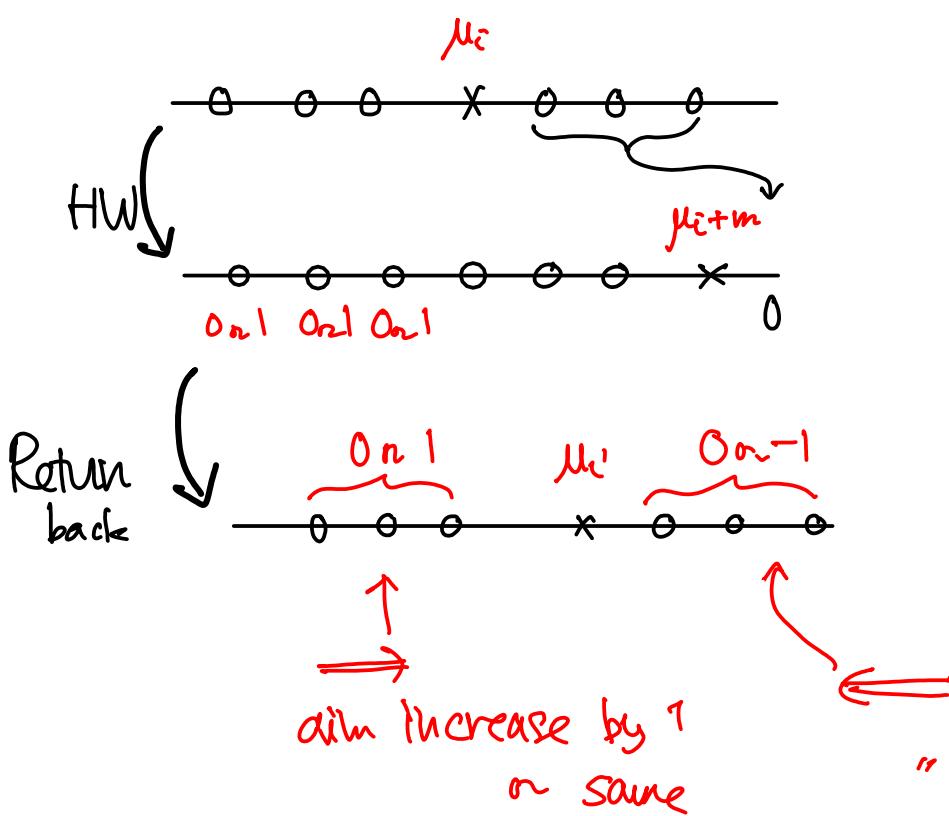
We collapse the triangular part except  
We unfold the circle to a line

$$\overleftarrow{\dots} \rightarrow \text{Tr}_{i-1}(t_i) \rightarrow \text{Tr}_i(t_i) \rightarrow \dots \rightarrow$$

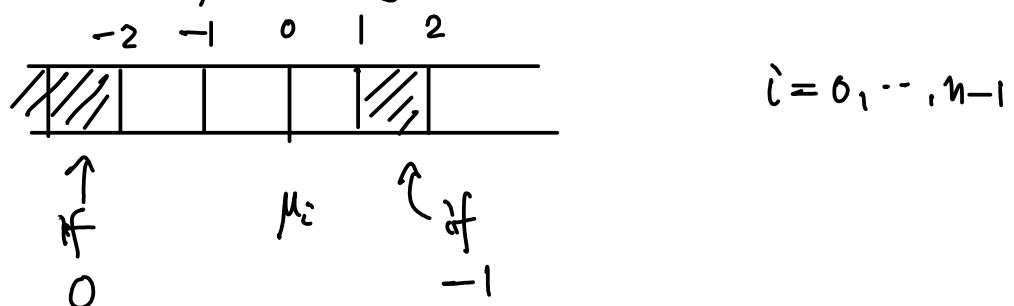
$\downarrow$

$\mathbb{C}_{x_i}$

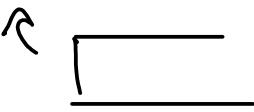
$\mu_i = \dim \text{Tr}_{i-1}(t_i) - \text{Tr}_i(t_i)$  as other summands have  $\frac{A_{x_i}}{\cong}$



We assign Maya diagram



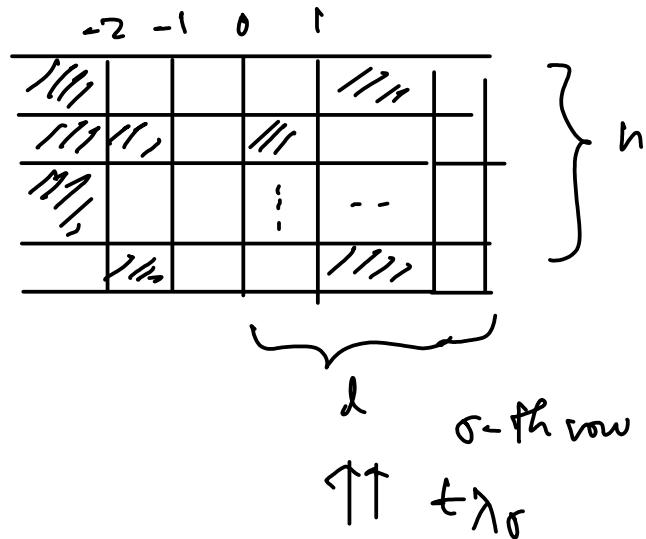
at left end



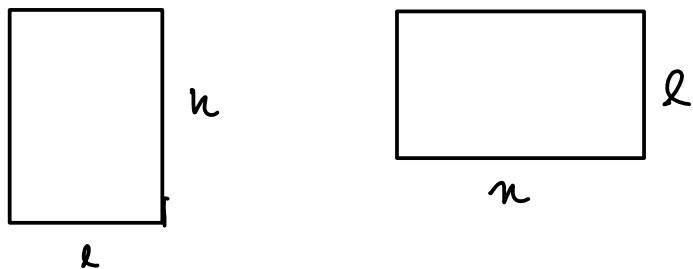
right end

$$\# \square \text{ in } \begin{array}{c} -2 \\ \leftarrow \end{array} \begin{array}{c} -1 \\ \uparrow \end{array} \begin{array}{c} 0 \\ \uparrow \end{array} \\ - \# \blacksquare \text{ in } \begin{array}{c} 0 \\ \rightarrow \end{array} \begin{array}{c} 1 \\ \uparrow \end{array} \begin{array}{c} 2 \\ \uparrow \end{array} = \mu_2$$

Combine  $i=0, \dots, n-1$



$$\text{Prop } e(\tilde{M}) = e(\tilde{M}(s \leftrightarrow x))$$



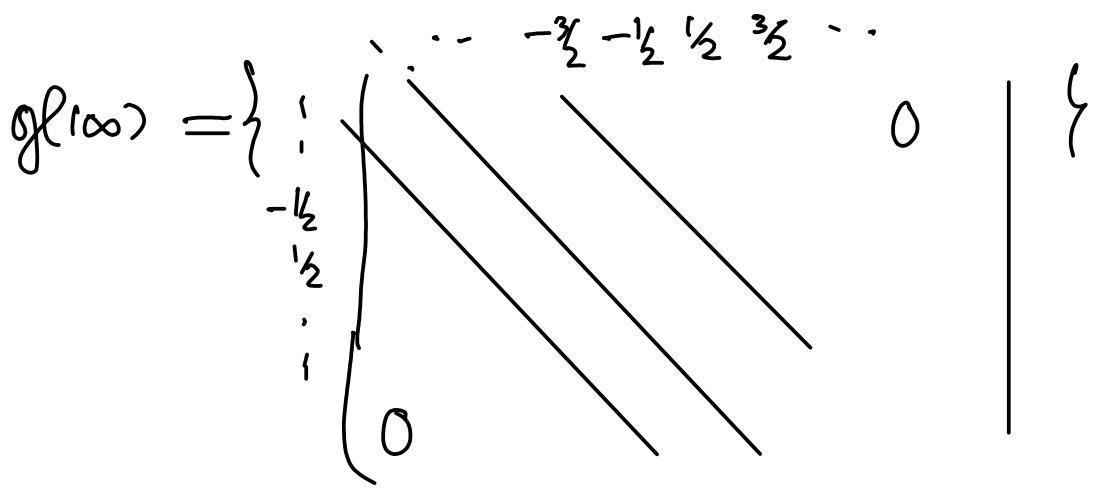
Maya diagram appears in representation theory  
of  $\widehat{\mathfrak{gl}}(\infty)$

$$\mathbb{C}^\infty = \langle v_{\frac{1}{2}+m} \mid m \in \mathbb{Z} \rangle$$

$$\bigwedge^{\infty} \mathbb{C}^\infty = \langle v_{i_1}, v_{i_2}, \dots \mid i_1 > i_2 > \dots \rangle$$

$i_3 \quad i_2 \quad i_1$

at right end



for sufficiently large

$\hat{gl}(\infty)$  : central extension s.t.  
of  $gl(\infty)$

$$\left[ \begin{array}{cccccc} \cdots & 1 & & & 0 & \\ & 0 & 1 & & & \\ & & 0 & 1 & & \\ & & & 0 & \ddots & \\ & & & & \ddots & \ddots \end{array} \right]$$

$$\hat{\mathcal{A}}(n) \subset \hat{gl}(\infty)$$

$$\text{Fock rep.} \curvearrowleft \wedge^{\infty} \mathbb{C}^{\infty}$$